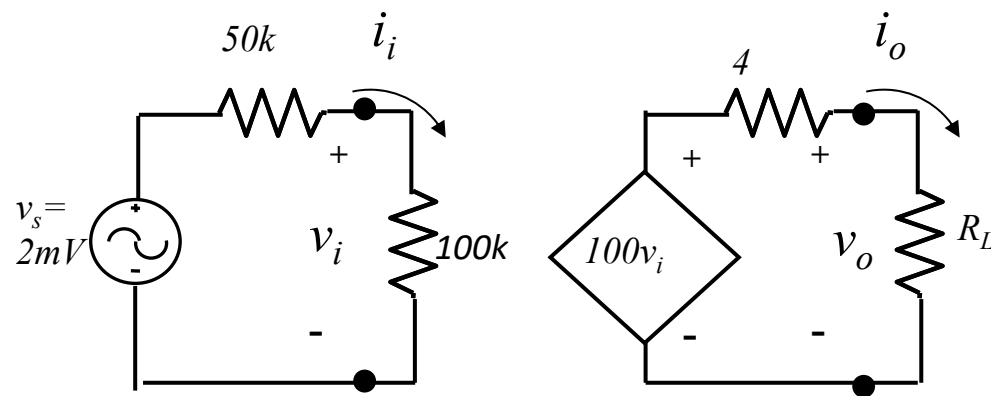


# BME 301

## 10-Amplifiers and Feedback

# Homework

1. For the following circuit, determine the value of  $R_L$  to maximize the power gain for this circuit. Provide a proof. Which value of  $R_L$  makes the better design and why?



# Homework

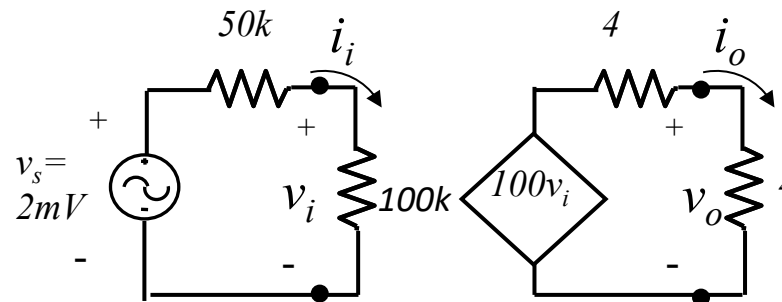
- For the following circuit, determine the value of  $R_L$  to maximize the power gain for this circuit. Provide a proof. Which value of  $R_L$  makes the better design and why?

To determine the best value of  $R_L$ ,  
calculate the power gain,

$$G = \frac{v_o i_o}{v_i i_i} = \frac{v_o}{v_i} \times \frac{i_o}{i_i} = A_v A_i$$

$$= \frac{\frac{R_L}{R_L + r_o} A v_i}{\frac{v_i}{r_i}} \times \frac{A v_i}{\frac{v_i}{r_i}} = \frac{R_L}{(R_L + r_o)^2} r_i A^2$$

take the derivative of it with respect to  $R_L$   
and set it equal to zero:



$$\frac{dG}{dR_L} = \frac{1}{(R_L + r_o)^2} r_i A^2 - 2 \frac{R_L}{(R_L + r_o)^3} r_i A^2 = 0$$

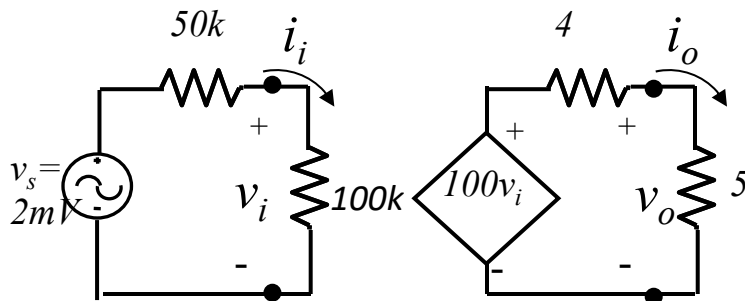
Now solve for  $R_L$

$$R_L + r_o = 2R_L \Rightarrow R_L = r_o$$

That is, make  $R_L =$  to the output impedance,  $r_o$ ,  
and the power gain will be maximized. In this  
case  $R_L = 5\Omega$ .

# Homework

1. For the following circuit, calculation the gains  $A_v$ ,  $A_{vs}$ ,  $A_i$ , and power gain for  $R_L = 2, 4, 6$  ohms. Which value of  $R_L$  makes the better design and why?



$$i_i = \frac{2mV}{50k + 100k} = \frac{2 \times 10^{-3}}{150 \times 10^3} = .013 \mu A$$

$$v_i = i_i 100k = 1.33mV$$

$$i_o = \frac{100 \times 1.33mV}{5} = 26.6mA$$

$$v_o = 2 \times 26.6mA = 53.3mV$$

$$A_{vs} = \frac{v_o}{v_s} = \frac{53.3mV}{2mV} = 26.6$$

$$A_v = \frac{v_o}{v_i} = \frac{53.3mV}{1.33mV} = 37$$

$$A_i = \frac{i_o}{i_i} = \frac{26.6mA}{.013 \mu A} = 2.05 \times 10^6$$

$$G = A_v \times A_i = 7.6 \times 10^7$$

# Homework

## 2. What are the benefits of negative feedback?

- Stabilization of Gain
- Reduction of Nonlinear Distortion
- Reduction of noise
- Control of input and output impedances
- Extension of Bandwidth

## 3. What are the problems with positive feedback?

- In stability unless instability is desired (e.g., timer)

# Homework

4. HONORS STUDENTS ADD THE FOLLOWING

Name 3 types of negative feedback applications.

Timers – In computer circuits

Schmitt Triggers – Level Detection

Oscillators – signal generation of sinusoids and square waves, for example.